

## Boost in an Arbitrary Direction

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**Abstract:** We exhibit the unimodular matrix generating, in special relativity, a boost with arbitrary direction, which is used to construct solutions of the Dirac equation for free particle.

**Key words:** Lorentz mapping - Unimodular matrix - Dirac 4-spinor - Boost in special relativity

### INTRODUCTION

Here we consider the matrix  $B = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$  with  $\alpha\delta - \beta\gamma = 1$  for the values:

$$\begin{aligned} \alpha &= \cosh\left(\frac{\phi}{2}\right) - \frac{v_z}{v} \sinh\left(\frac{\phi}{2}\right), & \delta &= \cosh\left(\frac{\phi}{2}\right) + \frac{v_z}{v} \sinh\left(\frac{\phi}{2}\right), \\ \beta &= -\frac{1}{v} (v_x + i v_y) \sinh\left(\frac{\phi}{2}\right), & \gamma &= -\frac{1}{v} (v_x - i v_y) \sinh\left(\frac{\phi}{2}\right), \end{aligned} \quad (1)$$

where  $\phi$  is determined by the speed between the frames of reference:

$$\begin{aligned} \cosh \phi &= \tilde{\gamma} = \frac{1}{\sqrt{1-v^2}}, & \sinh \phi &= \frac{v}{c} \tilde{\gamma}, & v^2 &= v_x^2 + v_y^2 + v_z^2, & \vec{p} &= m \vec{v} = m_0 \tilde{\gamma} \vec{v}, \\ |\vec{p}| &= p = m v, & E^2 &= p^2 c^2 + m_0^2 c^4, & \cosh\left(\frac{\phi}{2}\right) &= \sqrt{\frac{E + m_0 c^2}{2 m_0 c^2}}, & \sinh\left(\frac{\phi}{2}\right) &= \sqrt{\frac{E - m_0 c^2}{2 m_0 c^2}}, \\ \tanh \phi &= \frac{v}{c}, & \tanh\left(\frac{\phi}{2}\right) &= \frac{\sinh \phi}{1 + \cosh \phi} = \frac{p c}{E + m_0 c^2}, & 2 \sinh^2\left(\frac{\phi}{2}\right) &= \cosh \phi - 1 = \tilde{\gamma} - 1, \end{aligned} \quad (2)$$

Then the parameters (1) generate a proper Lorentz transformation future preserving  $\tilde{x}^\mu = L^\mu_\lambda x^\lambda$  via the expressions [1-10]:

$$\begin{aligned} L^0_0 &= \frac{1}{2}(\alpha\bar{\alpha} + \beta\bar{\beta} + \gamma\bar{\gamma} + \delta\bar{\delta}), & L^1_0 &= \frac{1}{2}(\bar{\alpha}\gamma + \bar{\beta}\delta) + cc, & L^2_0 &= -\frac{i}{2}(\alpha\bar{\gamma} - \bar{\beta}\delta) + cc, \\ L^0_1 &= \frac{1}{2}(\bar{\alpha}\beta + \bar{\gamma}\delta) + cc, & L^1_1 &= \frac{1}{2}(\bar{\alpha}\delta + \beta\bar{\gamma}) + cc, & L^2_1 &= -\frac{i}{2}(\alpha\bar{\delta} + \beta\bar{\gamma}) + cc, \\ L^0_2 &= -\frac{i}{2}(\bar{\alpha}\beta + \bar{\gamma}\delta) + cc, & L^1_2 &= -\frac{i}{2}(\bar{\alpha}\delta + \beta\bar{\gamma}) + cc, & L^2_2 &= \frac{1}{2}(\bar{\alpha}\delta - \bar{\beta}\gamma) + cc, \\ L^0_3 &= \frac{1}{2}(\alpha\bar{\alpha} - \beta\bar{\beta} + \gamma\bar{\gamma} - \delta\bar{\delta}), & L^1_3 &= \frac{1}{2}(\bar{\alpha}\gamma - \bar{\beta}\delta) + cc, & L^2_3 &= -\frac{i}{2}(\alpha\bar{\gamma} + \bar{\beta}\delta) + cc, \\ L^3_0 &= \frac{1}{2}(\alpha\bar{\alpha} + \beta\bar{\beta} - \gamma\bar{\gamma} - \delta\bar{\delta}), & L^3_1 &= \frac{1}{2}(\bar{\alpha}\beta - \bar{\gamma}\delta) + cc, & L^3_2 &= -\frac{i}{2}(\bar{\alpha}\beta - \bar{\gamma}\delta) + cc, \\ L^3_3 &= \frac{1}{2}(\alpha\bar{\alpha} - \beta\bar{\beta} - \gamma\bar{\gamma} + \delta\bar{\delta}), & \alpha\delta - \beta\gamma &= 1, \end{aligned} \quad (3)$$

where  $cc$  means the complex conjugate of all the previous terms. Thus we obtain the following Lorentz symmetric matrix representing a boost in an arbitrary direction:

$$(L^\mu{}_\lambda) = \begin{pmatrix} \tilde{\gamma} & -\frac{v_x}{c}\tilde{\gamma} & -\frac{v_y}{c}\tilde{\gamma} & -\frac{v_z}{c}\tilde{\gamma} \\ -\frac{v_x}{c}\tilde{\gamma} & 1 + \frac{v_x^2}{v^2}(\tilde{\gamma} - 1) & \frac{v_x v_y}{v^2}(\tilde{\gamma} - 1) & \frac{v_x v_z}{v^2}(\tilde{\gamma} - 1) \\ -\frac{v_y}{c}\tilde{\gamma} & \frac{v_x v_y}{v^2}(\tilde{\gamma} - 1) & 1 + \frac{v_y^2}{v^2}(\tilde{\gamma} - 1) & \frac{v_y v_z}{v^2}(\tilde{\gamma} - 1) \\ -\frac{v_z}{c}\tilde{\gamma} & \frac{v_x v_z}{v^2}(\tilde{\gamma} - 1) & \frac{v_y v_z}{v^2}(\tilde{\gamma} - 1) & 1 + \frac{v_z^2}{v^2}(\tilde{\gamma} - 1) \end{pmatrix}, \quad (4)$$

That is [11]:

$$\tilde{t} = \tilde{\gamma} \left( t - \frac{1}{c^2} \vec{v} \cdot \vec{x} \right), \quad \vec{\tilde{x}} = \vec{x} + \left[ \frac{\tilde{\gamma}-1}{v^2} \vec{v} \cdot \vec{x} - \tilde{\gamma} t \right] \vec{v}. \quad (5)$$

On the other hand, the Dirac spinor obeys the transformation law [11, 12]:

$$\tilde{\psi}(\tilde{x}^\mu) = S(L) \psi(x^\mu). \quad (6)$$

For a non-singular matrix  $S$  such that:

$$L^\mu{}_\nu S \gamma^\nu = \gamma^\mu S, \quad (7)$$

Involving the gamma matrices. The Dirac equation for spin-1/2 particles [11-14]:

$$(i\gamma^\mu \partial_\mu - m_0)\psi = 0, \quad i = \sqrt{-1}, \quad \partial_\mu = \frac{\partial}{\partial x^\mu}, \quad (8)$$

where  $\psi$  is a 4-spinor with the  $\gamma^\mu$  matrices verifying the anticommutator:

$$\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu} I_{4 \times 4}, \quad (g^{\mu\nu}) = \text{Diag}(1, -1, -1, -1). \quad (9)$$

In the Dirac-Pauli (or standard) representation:

$$\gamma_D^0 = \begin{pmatrix} I & 0 \\ 0 & -I \end{pmatrix}, \quad \gamma_D^j = \begin{pmatrix} 0 & \sigma_j \\ -\sigma_j & 0 \end{pmatrix}, \quad j = 1, 2, 3, \quad (10)$$

With the Pauli matrices:

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad (11)$$

The transformation law of  $\psi$ , under the orthochronic and proper Lorentz group is governed by the matrix [10, 15]:

$$S = \begin{pmatrix} A & C \\ C & A \end{pmatrix}, \quad A = \frac{1}{2} \begin{pmatrix} \bar{\alpha} + \delta & \bar{\beta} - \gamma \\ \bar{\gamma} - \beta & \alpha + \bar{\delta} \end{pmatrix}, \quad C = \frac{1}{2} \begin{pmatrix} \bar{\alpha} - \delta & \bar{\beta} + \gamma \\ \bar{\gamma} + \beta & \bar{\delta} - \alpha \end{pmatrix}, \quad (12)$$

Verifying (6); therefore, (1) and (12) imply the following matrix which allows to relate Dirac 4-spinors between frames of references connected by an arbitrary boost:

$$S = \cosh\left(\frac{\phi}{2}\right) \begin{pmatrix} I & G \\ G & I \end{pmatrix}, \quad S^{-1} = \cosh\left(\frac{\phi}{2}\right) \begin{pmatrix} I & -G \\ -G & I \end{pmatrix}, \quad G = -\frac{c}{E + m_0 c^2} \begin{pmatrix} p_z & p_x - i p_y \\ p_x + i p_y & -p_z \end{pmatrix}, \quad (13)$$

where  $p_j = mv_j$ ,  $j = x, y, z$ .

If a particle is at rest, then (8) admits the solutions [11]:

$$\psi_I^0 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} e^{-\frac{i}{\hbar}Et}, \quad \psi_{II}^0 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} e^{-\frac{i}{\hbar}Et}, \quad \psi_{III}^0 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} e^{\frac{i}{\hbar}Et}, \quad \psi_{IV}^0 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} e^{\frac{i}{\hbar}Et}, \quad (14)$$

with  $E = m_0 c^2$  and  $Et = p_\mu x^\mu$ . Thus, the corresponding 4-spinors for a free particle with velocity  $\vec{v}$  are given by  $\psi_K = S^{-1} \psi_K^0$ ,  $K = I, \dots, IV$ , hence:

$$\begin{aligned} \psi_I &= \cosh\left(\frac{\phi}{2}\right) \begin{pmatrix} 1 \\ 0 \\ \frac{c p_z}{E + m_0 c^2} \\ \frac{c(p_x + i p_y)}{E + m_0 c^2} \end{pmatrix} e^{-\frac{i}{\hbar}p_\mu x^\mu}, & \psi_{II} &= \cosh\left(\frac{\phi}{2}\right) \begin{pmatrix} 0 \\ 1 \\ \frac{c(p_x - i p_y)}{E + m_0 c^2} \\ -\frac{c p_z}{E + m_0 c^2} \end{pmatrix} e^{-\frac{i}{\hbar}p_\mu x^\mu}, \\ \psi_{III} &= \cosh\left(\frac{\phi}{2}\right) \begin{pmatrix} \frac{c p_z}{E + m_0 c^2} \\ \frac{c(p_x + i p_y)}{E + m_0 c^2} \\ 1 \\ 0 \end{pmatrix} e^{\frac{i}{\hbar}p_\mu x^\mu}, & \psi_{IV} &= \cosh\left(\frac{\phi}{2}\right) \begin{pmatrix} \frac{c(p_x - i p_y)}{E + m_0 c^2} \\ -\frac{c p_z}{E + m_0 c^2} \\ 0 \\ 1 \end{pmatrix} e^{\frac{i}{\hbar}p_\mu x^\mu}, \end{aligned} \quad (15)$$

with the quantities (2), in agreement with the literature [11, 12].

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