Mannheim Curves

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Abstract: In this paper, we study non-geodesic biharmonic curves in the Heisenberg group Heis³. We characterize Mannheim curves in terms of its biharmonic partner curves in the Heisenberg group Heis³.

Key words: Heisenberg group · Biharmonic curve · Mannheim curve

Recently, there has been a growing interest in the theory of biharmonic maps, which can be divided into two main research directions. On one hand, the differential geometric aspect has driven attention to the construction and called the bitension field of ϕ . The operator Δ_{ϕ} is the of examples and classification results. On the other hand, rough Laplacian acting on $\Gamma(\phi^*TM)$ given by: the analytic aspect from the point of view of PDE are solutions of a fourth order strongly elliptic semilinear PDE.

N and *M*, respectively. We use the sign convention: where ${e_i}_{i=1}^n$ is a local orthonormal frame field of *N*. Let (*N*, *h*) and (*M*, *g*) be Riemannian manifolds. Denote by R^N and R the Riemannian curvature tensors of

$$
R^{N}(X,Y) = [\nabla_X, \nabla_Y] - \nabla_{[X,Y]}, X, Y \in \Gamma(TN).
$$

For a smooth map ϕ : $N \rightarrow M$, the Levi-Civita connection ∇ of (N, h) induces a connection ∇^{ϕ} on the pull-back bundle:

$$
\varphi^*TM =_{p \in N} T_{\varphi(p)}M.
$$

of ϕ . A map ϕ is said to be harmonic if its tension field are said to be proper. It is well known that proper vanishes identically. A smooth map $\phi: N \rightarrow M$ is said to be biharmonic maps, that is, biharmonic functions, play an biharmonic if it is a critical point of the bienergy important role in elasticity and hydrodynamics. functional: In this paper, we study non-geodesic biharmonic

$$
E_2(\varphi) = \int_N \frac{1}{2} |\mathsf{T}(\varphi)|^2 \, d\nu_h.
$$

INTRODUCTION The Euler--Lagrange equation of the bienergy is given by $T_2(\phi) = 0$. Here the section $T_2(\phi)$ is defined by:

$$
T_2(\varphi) = \Delta_{\varphi} T(\varphi) + \text{tr} R(T(\varphi), d\varphi) d\varphi, \qquad (1.1)
$$

$$
\Delta_{\varphi} := -\sum_{i=1}^{n} \left(\nabla^{\varphi}_{e_i} \nabla^{\varphi}_{e_i} - \nabla^{\varphi}_{\nabla^N_{e_i} e_i} \right),
$$

In particular, if the target manifold *M* is the Euclidean space E^m , the biharmonic equation of a map $\phi: N \to E^m$ is:

 $\Delta_h \Delta_h \phi = 0$,

where Δ _{*h*} is the Laplace--Beltrami operator of (N, h) .

The section $T(\phi)$: = tr $\nabla^{\phi}d\phi$ is called the tension field the converse is not true. Nonharmonic biharmonic maps Clearly, any harmonic map is biharmonic. However,

> Mannheim curves in terms of its biharmonic partner curves in the Heisenberg group Heis³. We characterize curves in the Heisenberg group Heis³.

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Heisenberg Group Heis³: Heisenberg group Heis³ can be seen as the space $R³$ endowed with the following multipilcation:

$$
(\overline{x}, \overline{y}, \overline{z})(x, y, z) = (\overline{x} + x, \overline{y} + y, \overline{z} + z - \frac{1}{2}\overline{x}y + \frac{1}{2}x\overline{y})
$$
(2.1)

Heis³ is a three-dimensional, connected, simply connected and 2-step nilpotent Lie group.

The Riemannian metric *g* is given by:

 $g = dx^{2} + dy^{2} + (dz + \frac{y}{2}dx - \frac{x}{2}dy)^{2}.$

$$
e_1 = \frac{\partial}{\partial x} - \frac{y}{2} \frac{\partial}{\partial z}, e_2 = \frac{\partial}{\partial y} + \frac{x}{2} \frac{\partial}{\partial z}, e_3 = \frac{\partial}{\partial z},
$$
(2.2)

for which we have the Lie products $[e_1, e_2] = e_3$, $[e_2, e_3] = A$ successful key to study the geometry of a curve is

$$
\nabla_{e_1} e_1 = \nabla_{e_2} e_2 = \nabla_{e_3} e_3 = 0, \qquad \nabla_{e_1} e_2 = -\nabla_{e_2} e_1 = \frac{1}{2} e_3,
$$

$$
\nabla_{e_1} e_3 = \nabla_{e_3} e_1 = -\frac{1}{2} e_2, \qquad \nabla_{e_2} e_3 = \nabla_{e_3} e_2 = \frac{1}{2} e_1.
$$

We adopt the following notation and sign Serret formulas: convention for Riemannian curvature operator on Heis³ defined by: $\nabla_{\mathbf{T}} \mathbf{T} = \kappa \mathbf{N}, \quad \nabla_{\mathbf{T}} \mathbf{N} = -\kappa \mathbf{T} - \tau \mathbf{B}, \quad \nabla_{\mathbf{T}} \mathbf{B} = \tau \mathbf{N}.$ (3.2)

$$
R(X,Y)Z = -\nabla_X \nabla_Y Z + \nabla_Y \nabla_X Z + \nabla_{X,Y} Z,
$$

$$
R(X, Y, Z, W) = g(R(X, Y)Z, W),
$$

where X, Y, Z, W are smooth vector fields on Heis³. The components ${R_{ijkl}}$ of *R* relative to ${e_1, e_2, e_3}$ are defined by: **Theorem 3.1:** (see [11]) Let γ : $I \rightarrow Heis_3$ be a non-geodesic

$$
g(R(e_1, e_j) e_k, e_l) = R_{ijkl}
$$

The non-vanishing components of the above tensor

$$
R_{121} = -\frac{3}{4}e_2, \quad R_{131} = \frac{1}{4}e_3, \quad R_{122} = \frac{3}{4}e_1,
$$

$$
R_{232} = \frac{1}{4}e_3, \quad R_{133} = -\frac{1}{4}e_1, \quad R_{233} = -\frac{1}{4}e_2,
$$

and

$$
R_{1212} = -\frac{3}{4}, \quad R_{1313} = R_{2323} = \frac{1}{4}.
$$
 (2.3)

Let $I \subset \mathbb{R}$ be an open interval and $\gamma: I \to (N, h)$ be a curve The Lie algebra of Heis³ has an orthonormal basis: $\tau(\gamma) = \nabla \gamma'$ and the biharmonic map equation (1.1) reduces **Biharmonic Curves in the Heisenberg Group Heis³:** parametrized by arc length on a Riemannian manifold. Putting $T = \gamma'$, we can write the tension field of γ as to:

$$
\nabla_{\mathbf{T}}^3 \mathbf{T} + R(\mathbf{T}, \nabla_{\mathbf{T}} \mathbf{T}) \mathbf{T} = 0.
$$
 (3.1)

 $[e_3, e_1 = 0 \text{ with } g = (e_1, e_1) = g(e_2, e_2) = g(e_3, e_3) = 1.$ We to use the Frenet frames along the curve, which is recalled obtain: $\frac{1}{2}$ in the following. Let γ : $I \rightarrow Heis^3$ be a curve on *Heis*³ frame fields tangent to Heis³ along γ defined as follows: parametrized by arc length. Let {**T**,**N**,**B**) be the Frenet *T* is the unit vector field γ tangent to γ , **N** is the unit vector field in the direction of $\nabla_{\mathbf{T}}\mathbf{T}$ (normal to γ) and *B* is chosen so that {**T**,**N**,**B**} is a positively oriented orthonormal basis. Then, we have the following Frenet-

$$
\nabla_{\mathbf{T}} \mathbf{T} = \kappa \mathbf{N}, \quad \nabla_{\mathbf{T}} \mathbf{N} = -\kappa \mathbf{T} - \tau \mathbf{B}, \quad \nabla_{\mathbf{T}} \mathbf{B} = \tau \mathbf{N}, \tag{3.2}
$$

while the Riemannian curvature tensor is given by: With respect to the orthonormal basis $\{e_1, e_2, e_3\}$ we can where $\kappa = |\nabla_{\mathbf{T}} \mathbf{T}|$ is the curvature of γ and τ is its torsion. write:

$$
\mathbf{T} = T_1 \mathbf{e}_1 + T_2 \mathbf{e}_2 + T_3 \mathbf{e}_3, \qquad \mathbf{N} = N_1 \mathbf{e}_1 + N_2 \mathbf{e}_2 + N_3 \mathbf{e}_3,
$$

$$
\mathbf{B} = \mathbf{T} \times \mathbf{N} = B_1 \mathbf{e}_1 + B_2 \mathbf{e}_2 + B_3 \mathbf{e}_3.
$$

non-geodesic biharmonic curve if and only if: curve on *Heis*³ parametrized by arc length. Then γ is a

The non-vanishing components of the above tensor
fields are:
$$
\kappa = \text{constant} \neq 0, \ \kappa^2 + \tau^2 = \frac{1}{4} - B_3^2, \ \tau' = N_3 B_3.
$$
 (3.3)

Theorem 3.2: (see [11]) Let γ : $I \rightarrow Heis^3$ be a non-geodesic curve on the Heisenberg group *Heis³* parametrized by arc length. If κ is constant and $N_1B_1 \neq 0$, then γ is not biharmonic.

Mannheim Curves in Heisenberg Group Heis3

Definition 4.1: Let γ , β : $I \rightarrow Heis_3$ be a unit speed nongeodesic curve. If there exists a corresponding relationship between the space curves γ and β such that, at the corresponding points of the curves, the principal normal lines of β coincides with the binormal lines of β , then β is called a Mannheim curve and γ a Mannheim From (2.2), we get: partner curve of β . The pair $\{\gamma, \beta\}$ is said to be a Mannheim pair.

Theorem 4.2: Let β : $I \rightarrow Heis^3$ be a Mannheim curve and γ its biharmonic partner curve. Then, the parametric equation of Mannheim curve β in terms of its biharmonic On the other hand, suppose that $\beta(s)$ is a Mannheim partner curve γ of β are: curve, then by the definition we can assume that:

$$
x_{\beta}(s) = \frac{\lambda}{\kappa} \sin \phi (\cos \phi - \Re) \cos[\Re s + \rho](\cos \phi + \frac{1}{2\Re} \sin^2 \phi)
$$

+
$$
\frac{1}{\Re} \sin \phi \sin[\Re s + \rho],
$$

$$
y_{\beta}(s) = \frac{\lambda}{\kappa} \sin \phi (\cos \phi - \Re) (\cos \phi + \frac{1}{2\Re} \sin^2 \phi) \sin[\Re s + \rho]
$$

(4.1)

$$
-\frac{1}{\Re} \sin \phi \cos[\Re s + \rho],
$$

$$
z_{\beta}(s) = (\cos \phi + \frac{1}{4\Re} \sin^2 \phi) s - \sin \phi,
$$

where ρ is constant of integration and

$$
\mathfrak{R} = \frac{\cos \phi \pm \sqrt{5(\cos \phi)^2 - 4}}{2}.
$$

Proof: The covariant derivative of the vector field **T** is:

$$
\nabla_{\mathbf{T}}\mathbf{T} = (T_1^{'} + T_2 T_3)\mathbf{e}_1 + (T_2^{'} - T_1 T_3)\mathbf{e}_2 + T_3^{'} \mathbf{e}_3.
$$
 (4.2)

$$
\mathbf{T} = \sin\phi\cos[\Re s + \rho]\mathbf{e}_1 + \sin\phi\sin[\Re s + \rho]\mathbf{e}_2 + \cos\phi\mathbf{e}_3,
$$
\n(4.3)

where
$$
\theta = \frac{\cos \phi \pm \sqrt{5(\cos \phi)^2 - 4}}{2}
$$
.

Using (2.2) in (4.3) , we obtain:

$$
\mathbf{T} = (\sin\phi\cos[\Re s + \rho], \sin\phi\sin[\Re s + \rho],
$$

\n
$$
\cos\phi - \frac{1}{2}y(s)\sin\phi\cos[\Re s + \rho] + \frac{1}{2}x(s)\sin\phi\sin[\Re s + \rho]).
$$

$$
\mathbf{T} = (\sin\phi\cos[\Re s + \rho], \sin\phi\sin[\Re s + \rho],
$$

\n
$$
\cos\phi + \frac{1}{2\Re}\sin^2\phi\cos^2[\Re s + \rho] + \frac{1}{2\Re}\sin^2\phi\sin^2[\Re s + \rho]).
$$

$$
\beta(s) = \gamma(s) + \lambda \mathbf{B}(s). \tag{4.4}
$$

From (4.2) and (4.3) , we deduce:

$$
\nabla_{\mathbf{T}}\mathbf{T} = \sin\phi\big(\cos\phi - \Re\big)\big(\sin[\Re s + \rho\,]\mathbf{e}_1 - \cos[\Re s + \rho\,]\mathbf{e}_2\big).
$$

By the use of Frenet-Serret formulas, we get:

$$
\mathbf{N} = \frac{1}{\kappa} \nabla_{\mathbf{T}} \mathbf{T} = \frac{1}{\kappa} [\sin \phi (\cos \phi - \Re)(\sin[\Re s + \rho] \mathbf{e}_1 - \cos[\Re s + \rho] \mathbf{e}_2)].
$$
\n(4.5)

Substituting (2.2) in (4.5) , we have:

$$
N = \frac{1}{\kappa} \sin \phi \big(\cos \phi - \Re \big) (\sin[\Re s + \rho], -\cos[\Re s + \rho], 0).
$$

Noting that $\mathbf{T} \times \mathbf{N} = \mathbf{B}$, we obtain:

is:
$$
\mathbf{B} = \frac{1}{\kappa} \sin \phi (\cos \phi - \Re) (\cos[\Re s + \rho](\cos \phi + \frac{1}{2\Re} \sin^2 \phi),
$$

(4.2)
$$
(\cos \phi + \frac{1}{2\Re} \sin^2 \phi) \sin[\Re s + \rho], -\sin \phi).
$$
 (4.6)

Thus using Theorem 3.2, we find: Finally, we substitute (4.3) and (4.6) into (4.4), we get (4.1). The proof is completed.

We can use Mathematica in Theorem 4.2, yields:

Corollary 4.3: Let $\gamma: I \rightarrow \mathbf{K}$ be a unit speed non-geodesic biharmonic partner curve of Mannheim curve β . Then, the Fig. 3: parametric equations of γ are:

$$
x(s) = \frac{1}{\Re} \sin \phi \sin[\Re s + \rho],
$$
\n(4.7)

$$
y(s) = -\frac{1}{\Re} \sin \phi \cos[\Re s + \rho],
$$

$$
z(s) = (\cos \phi + \frac{1}{4\Re} \sin^2 \phi)s,
$$

where $\Re \phi = \frac{\cos \phi \pm \sqrt{5(\cos \phi)^2 - 4}}{2}.$

Similarly, we can use Mathematica in Corollary 4.3, yields: J. Math., 17: 169-188.

If we use Mathematica both Mannheim curve and its biharmonic partner curve, we have:

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